

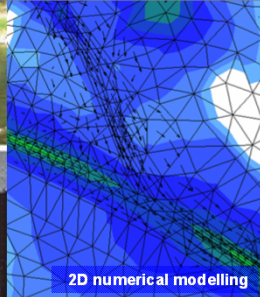


## Collection and Interpretation of Point Clouds of Terrestrial Laserscanning as a Basis for Hydraulic Flow Modelling



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Geodetic Institute, Institute of Water and River Basin Management

Terrestrial Laser Scanning
Photo
TLS point cloud
2D numerical modelling

KIT – The cooperation of Forschungszentrum Karlsruhe GmbH and Universität Karlsruhe (TH)


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## Background

- **Aim**  
Development of a hydrodynamic numerical model of a restored river reach
- **Such restored river reaches often show...**
  - a complex geometry of the riverbed (shallow /deep water zones, sills, flow obstacles,...)
  - structures on the bank / in the foreland
  - high diversity of vegetation



} → complex hydraulic situation


The creation of a hydraulic model of a nature-oriented reach requires a detailed field survey.

Example of a restored river section in the city of Lörrach (January 2008)




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## Acquisition of detailed geodata


- **Terrestrial Laser Scanning**
  - Advantages
    - highly detailed, exact survey of the ground, structures, vegetation
    - high speed of data-collection
  - Disadvantages
    - extensive efforts for data processing (rectification, thinning out, filtering)
    - no measuring of zones under water  
→ survey during low water  
→ combination with data collected by means of other survey methods




Research cooperation:  
Geodetic Institute (GIK)  
Institute for Water and River Basin Management (IWG)




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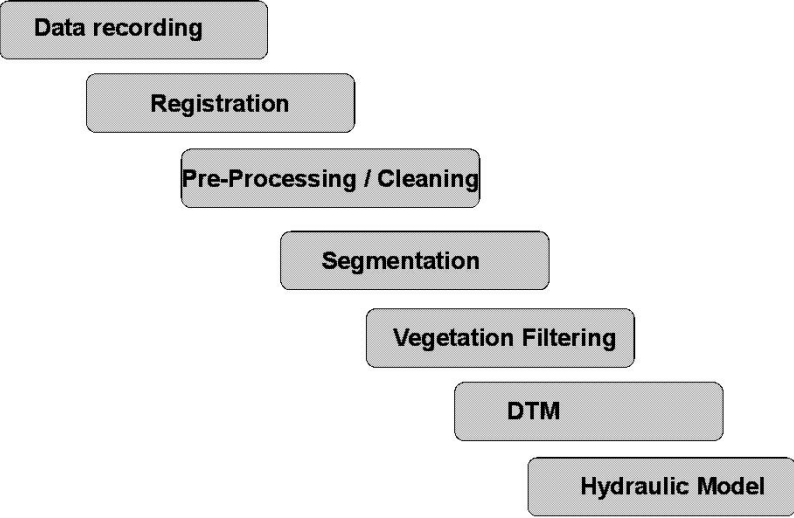
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
## Geometry Processing (Workflow)




```

graph TD
    A[Data recording] --> B[Registration]
    B --> C[Pre-Processing / Cleaning]
    C --> D[Segmentation]
    D --> E[Vegetation Filtering]
    E --> F[DTM]
    F --> G[Hydraulic Model]
  
```

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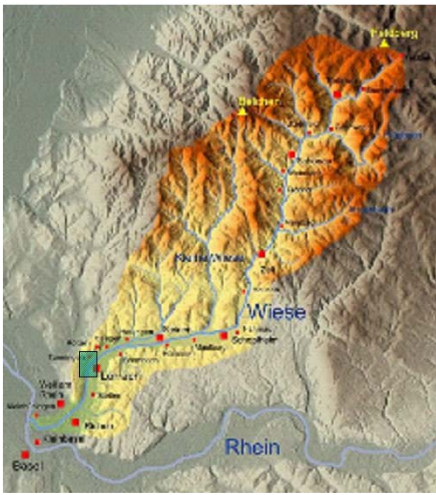
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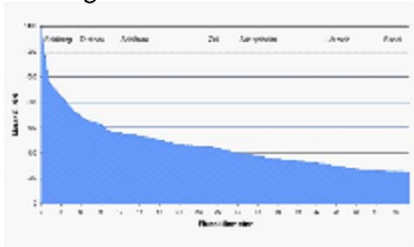
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## Area of Investigation

**Drainage area**




**Longitudinal section**




Area of Investigation  
200 x 50 m  
Low waterlevel

© de.wikipedia.org/wiki/Wiese\_(Fluss)

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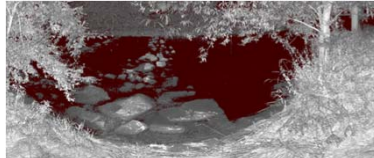
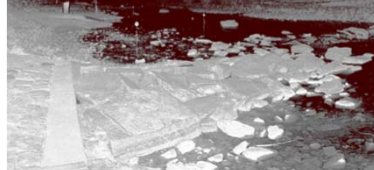
## Details of the Riverchannel (Wiese/Lörrach)




Bildquelle: Boettcher, RP Freiburg




Hydraulic structures

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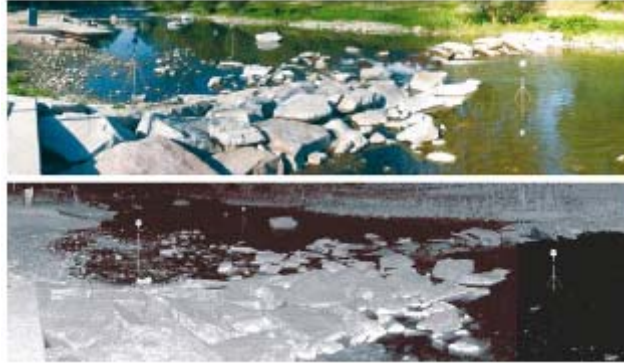
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## Pointcloud in the range of water



Pointcloud of the riverchannel characterized in

- Nearby the station:  
In shallow water the topography of riverchannel seemed to be captured
- Waterdepth > 20 cm  
small angle to watersurface } no reflected laserbeam
- Objects far from station give uncertain reflections

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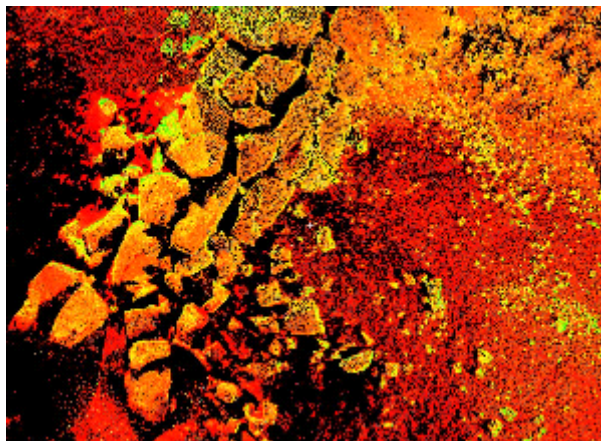


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## Laserbeam in/through water



Intensity of captured  
Laserbeam around a  
stone sill and shallow  
water

High intensity of stones

Low intensity of  
shallow water

No intensity in  
deep water

stones

shallow water

cross-section in pointcloud

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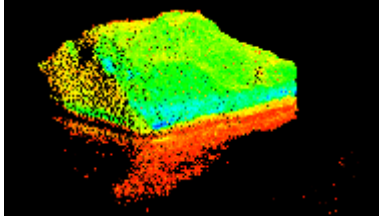


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## Optical Reflexion by Watersurface



Objects located in the water channel

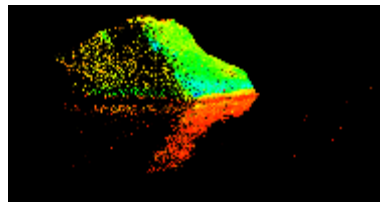
Partly above/under water

High reflections of visible parts

Low reflections of overflowed parts

Interpretation: Mirror of visible parts after optical reflexion of the laserbeam

no correction is possible



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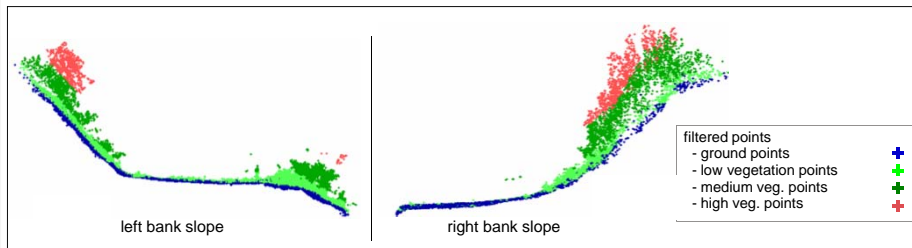


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## Processing of pointcloud

### Vegetation filtering

- Method: Hierarchic robust filtering (Software SCOP++<sup>(\*)</sup>), generally used for filtering of ALS data
- Modification of the weight function and the filtering parameters due to the smaller scale when handling TLS data
- works well in areas with vegetation



(\*) Inpho GmbH, Institute for Photogrammetry and Remote Sensing of the TU Wien (2007)

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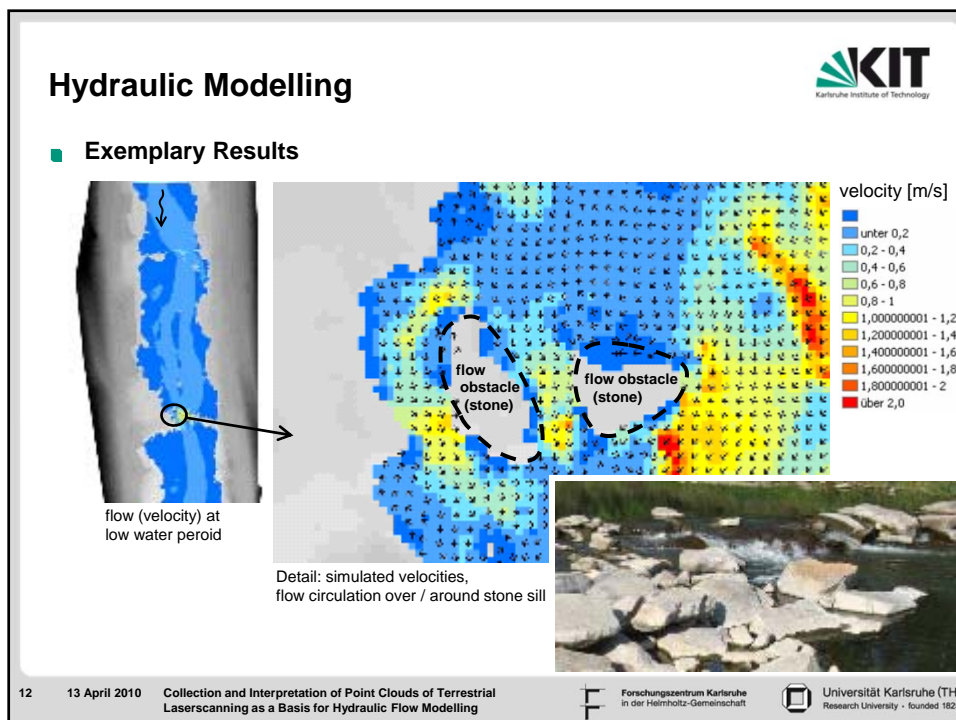
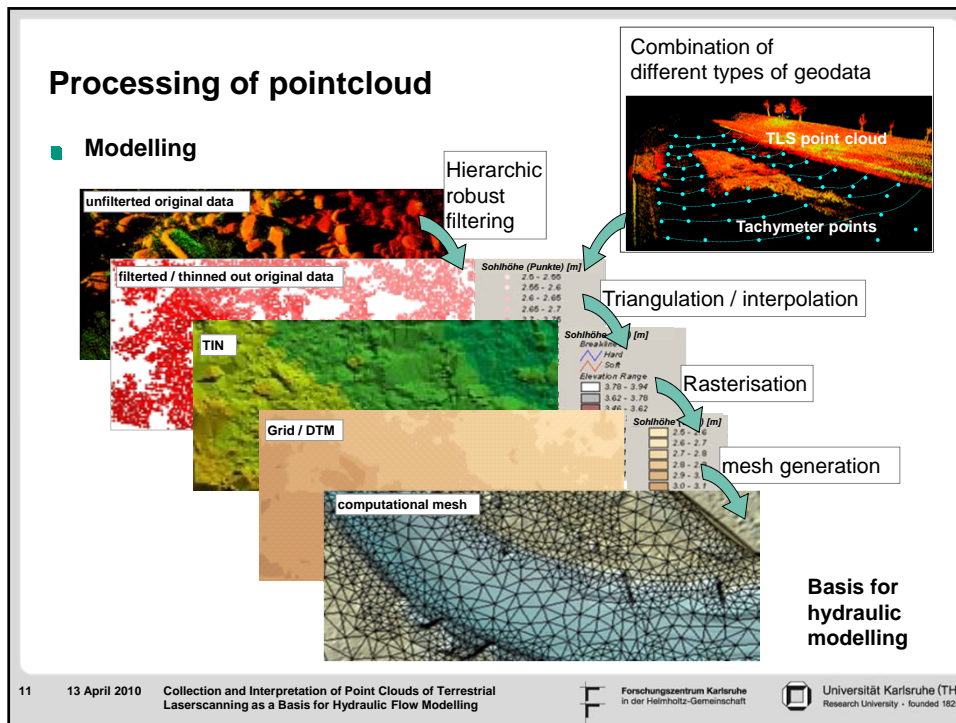
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Thank you for your attention!



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