

National Geodetic Survey

# **REAL-TIME POSITIONING GUIDELINES FOR THE INTERNATIONAL COMMUNITY-- THE ROLE OF FIG**

**FIG WORKWEEK  
TS 4C, 17 JUNE 2008  
STOCKHOLM, SWEDEN**



*Bill Henning, Senior Geodesist, PLS.*



A complete survey crew



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## **DYNAMIC RT TECHNOLOGY**

### **GLOBAL NAVIGATION SATELLITE SYSTEMS (GNSS)**

#### **POTENTIAL FUTURE DEVELOPMENTS (2005 – 2017?)**

**GPS MODERNIZATION – BLOCK IIF & III**

**GLONASS ENHANCEMENTS (K & M)**

**EUROPEAN UNION – GALILEO**

**CHINA – COMPASS**

**INDIA, JAPAN –?**

**115+ Satellites**

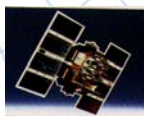
**Second and Third Civil Frequency - GPS**

**No Signal Encryption - GLONASS & GALILEO**

**More Robust Signal Transmissions**

**Real-Time Unaugmented 1 Meter (or better!) Accuracy**

**+ BETTER COMMUNICATION COVERAGE & TECHNOLOGY**



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## STANDALONE POSITIONING: BY 2017?

**UERE - 2008**

Error	Value
Ionosphere	4.0 meters
Clock	2.1 meters
Ephemeris	2.1 meters
Troposphere	0.7 meters
Receiver	0.5 meters
Multipath	1.0 meter
<b>Total</b>	<b>10.4 meters</b>

1-3 m

10.45 cm???

- Civil Code on L1
- Civil Code on L2
- New Code on L5

**BETTER RESISTANCE TO INTERFERENCE**

**FASTER AMBIGUITY RESOLUTION**

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## NTRIP STREAMS- EUROPE

Bundesamt für Kartographie und Geodäsie

Ntrip Streams Europe

NTRIP Real-Time GNSS Streams 060523 14:13 UTC

Networks

- IOS
- EUREF
- Misc
- GREF
- EGNOS
- SAPOS-BY
- SAPOS-BL
- SAPOS-BB
- SAPOS-SL
- SAPOS-HE
- SAPOS-MV
- SAPOS-NI
- SAPOS-TR
- ospos
- SIGNAL
- FNNREF
- SAT-INFO
- RCP
- EROPS
- GPSnet.dk
- FLGRO
- OrinSTAR
- SMPOS
- SGO
- Test
- EGNOS-HUN
- EGNOS-IBP
- EGNOS-FIN
- EGNOS-ITA
- BNet
- netPADO
- ASG
- EGNOS-NOR
- Orpheon
- Colnet
- 06-GPS
- VESOG
- CZEPOS

Legend:

- RAW
- DGPS
- RTK
- Other

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## PBO STATIONS

- **BINEX & RTCM 2.3**
- **2 – 2.25 TOTAL LATENCY**
- **SERVER IN BOULDER, CO**
- **60 STATIONS**

**PBO Network**

- Existing GPS
- Backbone
- GSN Backbone
- Volcanoes

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## IGS RT STATIONS

**Real Time Working Group**

[Home](#)
[Stations](#)
[Protocol](#)
[Data Products](#)
[Architecture](#)
[Software Tools](#)
[Network](#)
[FAQ's](#)
[Request Info](#)
[Pilot Project](#)

RT-IGS Prototype Tracking Network -- Click station to see the performance of active stations

This page has links to graphs showing the performance of the IGS Real-Time Network prototype. The network is currently being monitored in 0 hours by [NAVAL Research Canada, Geodetic Survey Station GSC](#). It is important to keep in mind that the performance statistics may reflect things that are outside the control of the agency responsible for a particular station. Network performance will be optimized at a future date.

Data Provided Among Contributing Agencies:

**60 STATIONS +/-**

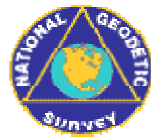
**UDP FORMAT**

**DATA-NRC**

**NTRIP-BKG**

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## CURRENT NGS ACTIVITY IN SUPPORT OF REAL-TIME POSITIONING



## OVERALL PROGRAM OBJECTIVE

- Ensure that geodetic issues are adequately addressed in operation and use of real-time positioning systems



## CHANGE IN ACCESSING THE NSRS BY PASSIVE TO ACTIVE MONUMENTATION

### EXAMPLE: GNSS DERIVED HEIGHTS

- NOS-NGS 58 WITH DRAFT ORTHO GUIDELINES- 0.05 m TO NSRS, 0.02 m LOCAL
- DGPS - 15 SECONDS, 0.5 TO 2 m
- OPUS > 4 HRS = 0.02 M (h), 0.05 (H)
- CORS- SAME AS OPUS
- OPUS-RS 15 MINUTES = 0.10 m
- SINGLE BASE RTK- "IT DEPENDS!"  
5 SECONDS (better than 0.03 m expected)
- RTN - "IT DEPENDS!"  
5 SECONDS ( better than 0.04 m expected)

PASSIVE

ACTIVE

STATIC

STATIC

REAL TIME

5 1/2 HOURS - HARN

30-45 MINUTES NETWORK

2-4 HOURS

10-30 MINUTES

5 SECONDS -  
3 MINUTES



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## RT ACCESS TO THE NSRS

- GUIDELINES, SPECS, STANDARDS
- ✓ SINGLE-BASE USER
- RTN PLANNING & NETWORK DESIGN
- RTN CONSTRUCTION/SITE EVALUATION
- RTN ADMINISTRATIVE
- RTN USER



**RTN TEAM -  
ADVISORS AND  
PARTNERS**

- STREAMING DATA FROM THE FOUNDATION CORS  
(**HEADQUARTERS RT TEAM**)
- REFERENCE STATION & USER POSITION MONITORING, DATA ARCHIVING, 60 DAY PLOTS = NGS 'VERIFICATION'



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## THE TWO DIRECTIONS OF REAL-TIME POSITIONING



- I. TOP DOWN: Overall Administrator's viewpoint- Alignment to the NSRS, coordinates, adjustments, Network spacing, Site requirements, Communication issues, Personnel, Cost/Benefit analysis, \$\$\$\$ , Partners



- II. USER UP: Best methods- Field techniques, GNSS knowledge, Knowing datum requirements, Knowing accuracy requirements, Calibrations, Applications, Data management

**CLASSICAL RT**.....**NETWORK RT (RTN)**



### USER EXPERTISE MEANS CONSIDERING:

- Multipath
- Position Dilution of Precision (PDOP)
- Baseline Root Mean Square (RMS)
- Number of satellites
- Elevation mask (or cut-off angle)
- Base accuracy- datum level, local level
- Base security
- Redundancy, redundancy, redundancy
- Part(s) Per Million Error (ppm)- iono, tropo models, orbit errors
- Space weather- sunspot numbers, solar maximum
- Geoid quality
- Site calibrations (a.k.a. Localizations)
- Bubble adjustment
- Latency, update rate
- Fixed and float solutions
- Accuracy versus Precision
- Signal to Noise Ratio (S/N or C/N0)
- Float and Fixed Solutions
- Carrier phase
- Code phase
- VHF/UHF radio communication
- CDMA/SIM/Cellular TCP/IP communication
- WGS 84 versus NAD 83, or other local datums
- GPS, GLONASS, Galileo, Compass Constellations



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## ATMOSPHERIC AND ORBIT ERROR SOURCES

**IONOSPHERE**  
300 KM±

The Ionosphere delay is inversely proportional to the frequency of the radio waves. Therefore, the delay can be calculated by measuring the difference in the travel times for the two GPS frequencies.

The slowing or refraction of the signal as it passes through the atmosphere can be viewed as an increase in path length called "path delay" with units of distance.

**TROPOSPHERE**  
80 KM±

The Troposphere slows both frequencies equally. Therefore, its delay must be modeled separately in the processing.

Total Atmospheric Delay:  
Tropo - wet (only 10%, but hard to model) & dry (hygrostatic). Integrated Precipitable Water Vapor (IPWV) models  
Iono - Total electron content (TEC) models & "L<sub>4</sub>" or linear combination of the frequencies  
Real Time positioning assumes that the atmospheric conditions are the same at the base and rover and does limited modeling.

PRN-A

0h 2h

(~30,000 km)

Legend:  
- actual orbit (oscillating)  
- broadcast orbit  
- precise orbit (final SP3)  
- Kepler orbit

**GRAPHIC SOURCE:**  
Ahn, Yong Won (M.Sc. thesis), (2005), Analysis of NGS CORS Network for GPS RTK Performance Using External NOAA Tropospheric Corrections Integrated with a Multiple Reference Station Approach. [UCGE Report 20211](#).

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**WHY SINGLE-BASE?**

- ACCOMMODATE LEGACY USERS
- CLOSEST BASE NETWORKS
- AREAS WITH NO CELL COVERAGE
- PROJECT SITE APPLICATIONS, SUCH AS MACHINE CONTROL

<http://www.ngs.noaa.gov/>

NATIONAL GEODETIC SURVEY  
USER GUIDELINES  
FOR CLASSICAL  
REAL-TIME GNSS POSITIONING

v. 2.0 April 2008

William Henning, lead author

**WHY EMPIRICAL?**

- PLETHORA OF VARIABLES
- TIMELINESS
- PORT TO RTN USERS
- DYNAMIC NATURE OF RT POSITIONING

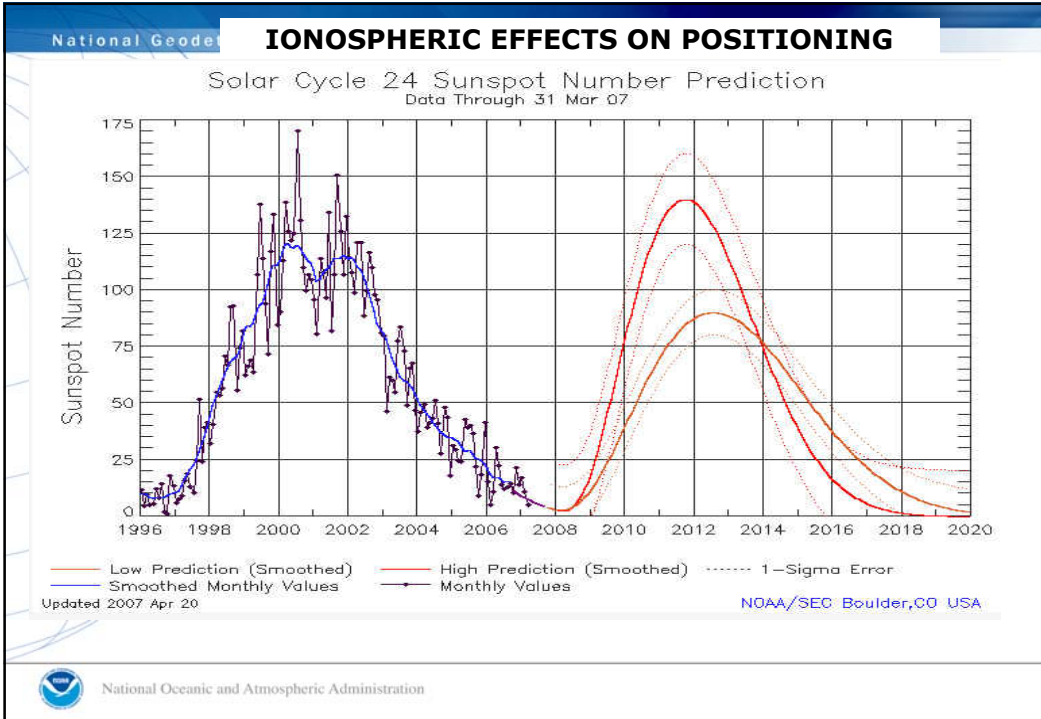
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## RT SINGLE-BASE ACCURACY CLASSES

ACCURACY CLASS SUMMARY TABLE				
	CLASS RT1	CLASS RT2	CLASS RT3	CLASS RT4
<b>ACCURACY (TO BASE)</b>	0.015 HORIZONTAL, 0.025 VERTICAL	0.025 HORIZONTAL, 0.04 VERTICAL	0.05 HORIZONTAL, 0.06 VERTICAL	0.15 HORIZONTAL, 0.25 VERTICAL
<b>REDUNDANCY</b>	≥ 2 LOCATIONS, 4-HOUR DIFFERENTIAL	≥ 2 LOCATIONS, 4-HOUR DIFFERENTIAL	NONE	NONE
<b>BASE STATIONS</b>	≥ 2, IN CALIBRATION PROJECT CONTROL	RECOMMEND 2 IN CALIBRATION	≥ 1, IN CALIBRATION	≥ 1, IN CALIBRATION RECOMMENDED
<b>PDOP</b>	≤ 2.0	≤ 3.0	≤ 4.0	≤ 6.0
<b>RMS</b>	≤ 0.01 M	≤ 0.015 M	≤ 0.03 M	≤ 0.05 M
<b>COLLECTION INTERVAL</b>	1 SECOND FOR 3-MINUTES	5 SECONDS FOR 1-MINUTE	1 SECOND FOR 15 SECONDS	1 SECOND FOR 10 SECONDS
<b>SATELLITES</b>	≥ 7	≥ 6	≥ 5	≥ 5
<b>BASELINE DISTANCE</b>	≤ 10 KM	≤ 15 KM	≤ 20 KM	ANY WITH FIXED SOLUTION
<b>TYPICAL APPLICATIONS</b>	PROJECT CONTROL CONSTRUCTION CONTROL POINTS CHECK ON TRAVERSE, LEVELS SCIENTIFIC STUDIES PAVING STAKE OUT	DENSIFICATION CONTROL TOPOGRAPHIC CONTROL PHOTOPPOINTS UTILITY STAKE OUT	TOPOGRAPHY CROSS SECTIONS AGRICULTURE ROAD GRADING SITE GRADING	SITE GRADING WETLANDS GIS POPULATION MAPPING ENVIRONMENTAL

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## RTN APPLICATIONS- INTERPOLATION AND MODELING OF ERROR FACTORS

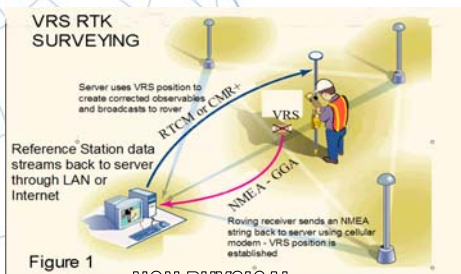


Figure 1

NON-PHYSICAL  
REFERENCE STATION

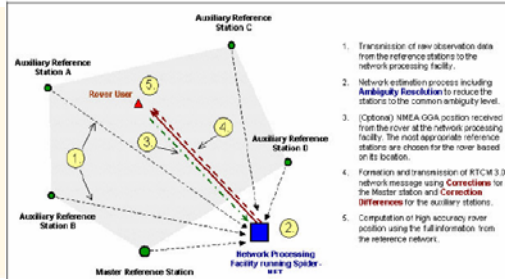
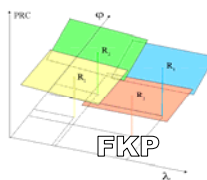


Figure 1: Generation of Master-Auxiliary corrections (MAX)

MASTER-AUXILIARY



## EXAMPLES OF RTN ADMINISTRATORS IN THE USA

- ACADEMIC/SCIENTIFIC
  - SPATIAL REFERENCE CENTERS
  - VARIOUS DOTS
  - COUNTY
  - CITY
  - GEODETTIC SURVEYS
  - MANUFACTURER
  - VENDOR NETWORKS
  - AGRICULTURE
  - MA & PA NETWORKS
- } **RAPIDLY GROWING**



## REAL TIME NETWORKS (RTN)



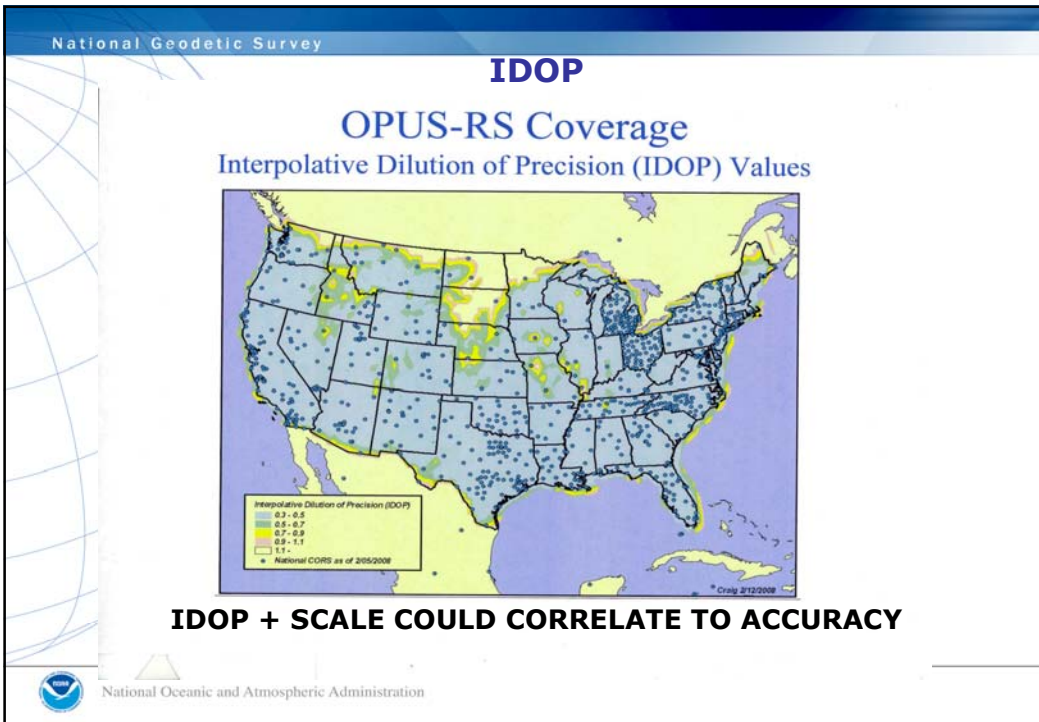
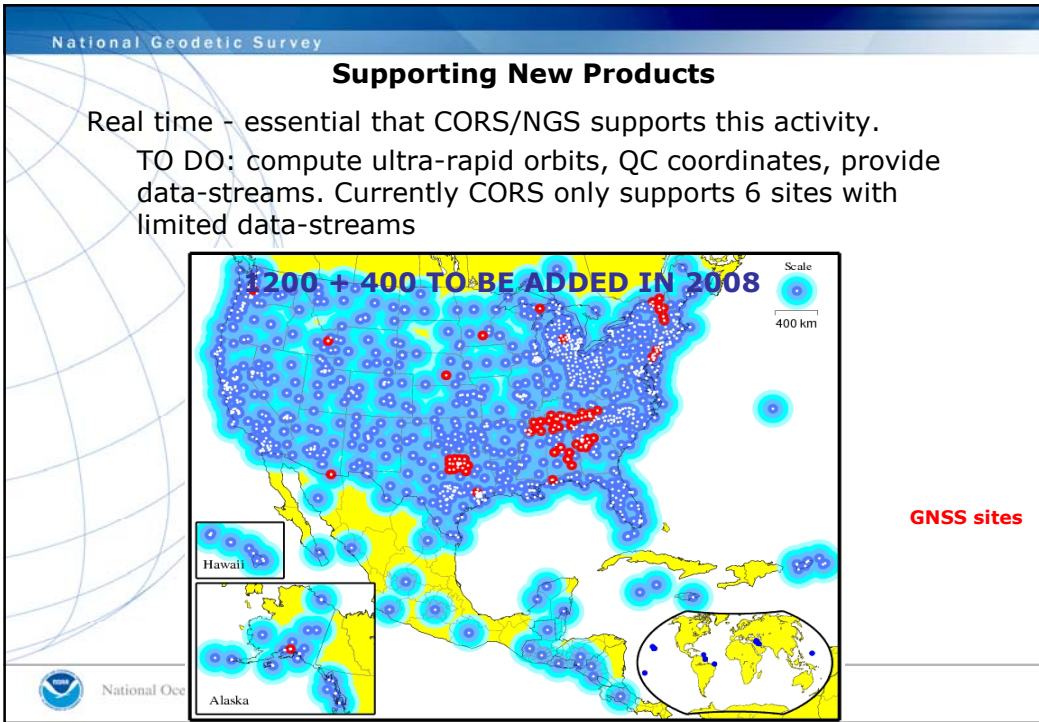
- PERHAPS MORE THAN 75 RTN EXIST IN THE USA WITH MANY IN THE PLANNING STAGES
- HOW ARE THEY ESTABLISHED?
- HOW ARE THEIR COORDINATES COMPUTED? ARE THEY CONSISTENT?
- HOW IS THE NETWORK ADJUSTED?
- HOW DOES THE RTN ALIGN TO THE NSRS?
- CAN USERS USE ANY MANUFACTURERS' EQUIPMENT IN THE RTN?
- DO OVERLAPPING NETWORKS GIVE THE SAME COORDINATES?
- WHAT ARE THE FIELD ACCURACIES?

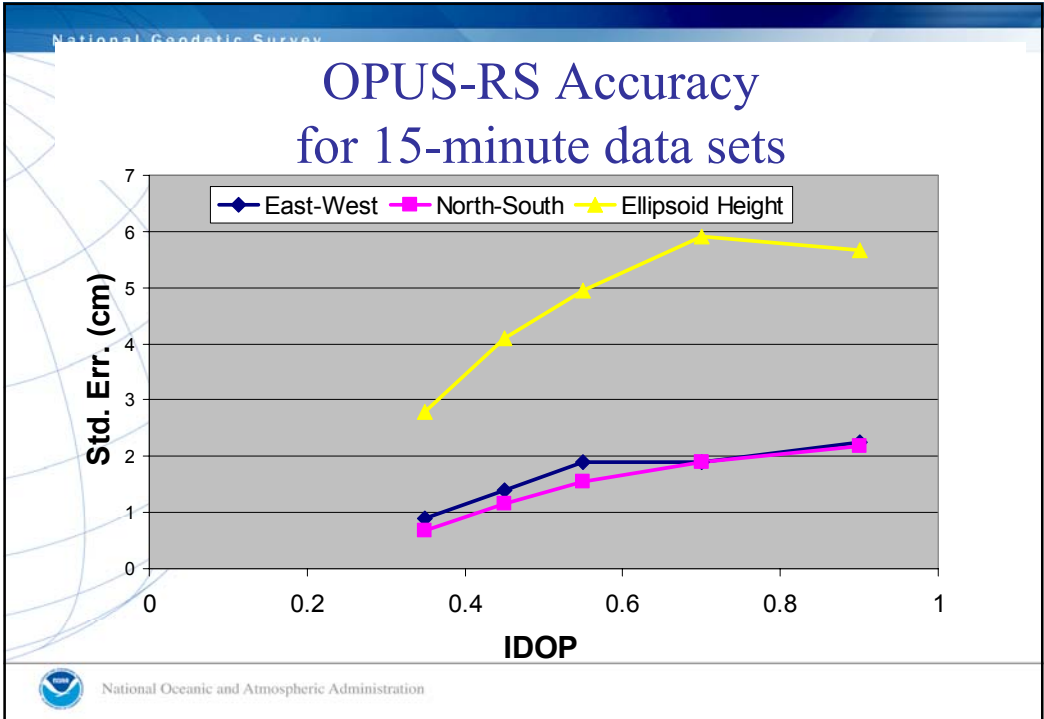
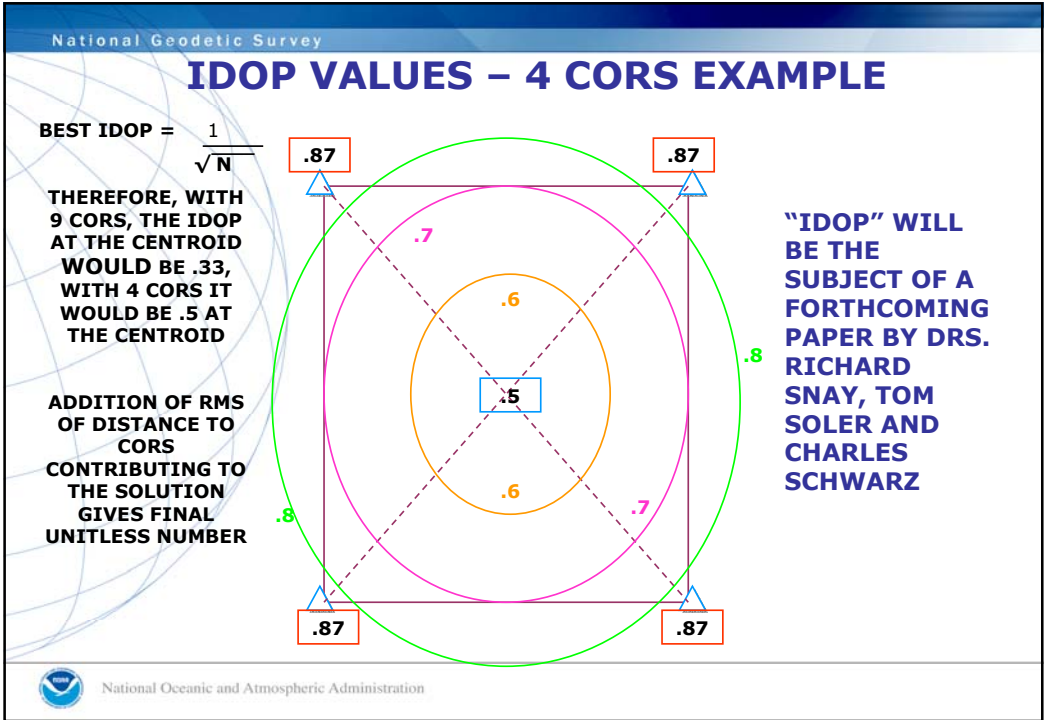


### Guidelines for Operating a Real-Time GNSS Network CHAPTER ONE -Achieving Consistency Among Positional Coordinates and Velocities

- ITRF 2000 or NAD 83  
3 recommendations:
- #1 Include a subnetwork of the RTN into the National CORS network.
- #2 For each reference station contained in the RTN, adopt values for its 3-dimensional positional coordinates (at a selected epoch date) and a velocity that are consistent with corresponding values adopted by NGS for reference stations in the National CORS network.
- #3 For each reference station in the RTN, use the Online Positioning User Service (OPUS) at <http://www.ngs.noaa.gov/OPUS/> to test for the continued consistency of its adopted positional coordinates and velocity on a daily basis, and revise the station's adopted coordinates and/or velocity if the tests reveal a need to do so.







## HOW ACCURATE ARE THE NATIONAL CORS?

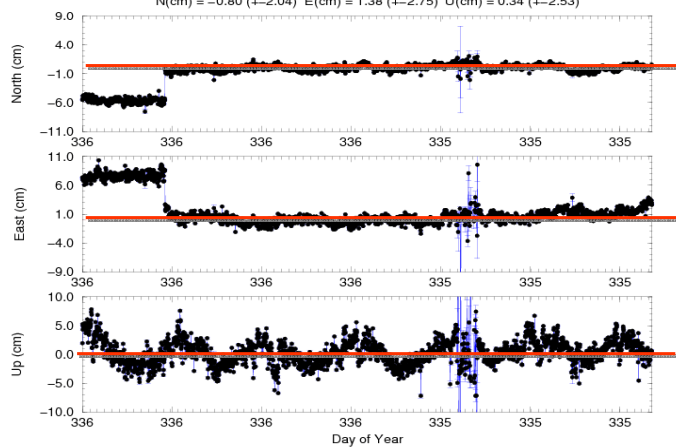
- EVALUATED TO 1 CM H, 2 CM V RELATIVE TO ITRF 2000 (2 CM/ 4 CM RELATIVE TO NAD 83 CHANGES COORDINATES)
- DAILY ADJUSTMENTS CONSTRAINED TO 5 CORS
- SEASONAL VARIATIONS
- DAILY VARIATIONS SEEN FROM OPUS-RS
- OCEAN & SOLID EARTH LOADING
- VELOCITIES FROM HTDP VS TIME SERIES



## GNAA- ALASKA CORS- DENALI QUAKE + SEASONAL VERTICAL MOVEMENT


GNAA: Adjusted Differences from A Priori

$N(\text{cm}) = -0.80 (+/-2.04)$   $E(\text{cm}) = 1.38 (+/-2.75)$   $U(\text{cm}) = 0.34 (+/-2.53)$



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## NGS Real Time Stream Team

Product Manager  
Richard Snay 

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Bill Henning  Pam Fromhertz 

CORS Data Streams  
Charlie Schwarz  Neil Weston  Giovanni Sella 


IT Team  
Bruce Sailer  Hong Chen  Sky Chaleff 

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## ISO GUIDELINES

- The International Standard 172, Secretariat for "GNSS field measurement systems in real-time kinematic (RTK)"
- <http://www.iso.org/iso/committee/icsedit.htm?cs=172>
- ".....are being evaluated"



INTERNATIONAL ORGANIZATION FOR STANDARDIZATION · МЕЖДУНАРОДНАЯ ОРГАНИЗАЦИЯ ПО СТАНДАРТИЗАЦИИ · ORGANISATION INTERNATIONALE DE NORMALISATION

DRAFT INTERNATIONAL STANDARD ISO/DIS 17123-8

ISO/TC 172/SC 6      Secretariat: SNV


Voting begins on: 2006-08-18      Voting terminates on: 2007-01-18

committee meeting "RTK" [detail.](#)

**Optics and optical instruments — Field procedures for testing geodetic and surveying instruments —**  
**Part 8: GNSS field measurement systems in real-time kinematic (RTK)**

*Optique et instruments d'optique — Méthodes d'essai sur site pour les instruments géodésiques et d'observation —*  
*Partie 8: Systèmes de mesure GNSS sur site en temps réel cinématique*

ICS 17.180.30

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## ISO RT GNSS EQUIPMENT TEST PROCEDURES

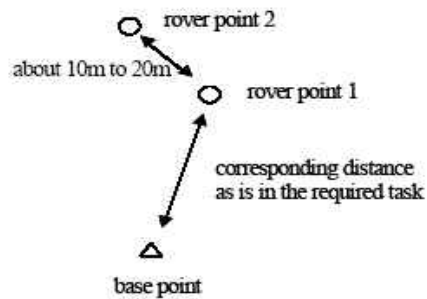


Figure 1 — Configuration of the field test network

**SERIES OF 5 LOCATIONS AT ROVER POINTS 1 & 2, SPACED 5 MINUTES APART**

### ***SIMPLIFIED TEST:***

- 1 SERIES COMPARED TO INDEPENDENTLY OBTAINED MEASUREMENTS OF DISTANCE (SPACING) AND HEIGHT  $\leq 3$  mm

### ***FULL TEST:***

- 3 SERIES COMPARED TO INDEPENDENTLY OBTAINED MEASUREMENTS OF DISTANCE (SPACING) AND HEIGHT  $\leq 3$  mm

- DEVELOP STATISTICAL TESTS VIA LEAST SQUARES METHODS

All measurements must fall within the manufacturer's deviation tolerances for horizontal and vertical precision (or if these are unavailable, 15 mm horizontal and 25 mm vertical). Temperature and general weather conditions are noted by the observer.



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## FIG COMMISSION 5

- The Commission 5 delegates must become familiar with the ISO/TC172 standards as a building block.
- National survey organizations, such as NGS, should draft their best practices for real-time positioning – both for classical single-base and RTN methodologies.
- Commission 5, workgroup 5.1, in charge of standards, quality assurance and calibration, should be tasked with compiling these best practices and preparing a summary for review by the international surveying community.



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COORDINATE SYSTEMS
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DIRECTION OF THE NGS

